

Curriculum Plans: Year 12 (Maths)

	Topic	Knowledge: By the end of the unit students will know:	Skills: What skills will students have developed by the end of this unit?	Key terms: What new key terms and vocabulary will be learnt in this unit?	Summative Assessment: How will pupils be assessed in this unit?
Michaelmas 1	1) Quadratic Functions Equations & Inequalities 2) Graphs and transformations 3) Circles 4) Algebraic Methods 5) Trigonometric Ratios 6) Radians	<ul style="list-style-type: none"> • Solving quadratic Equations • Completing the square • Quadratic Graphs • The Discriminant • Modelling with Quadratics • Simultaneous equations • Inequalities • Graphs of functions • Points of Intersections • Transforming Graphs • Midpoints and Perpendicular Bisectors • Equation of a circle • Intersections of straight lines and circles • Tangent and Chord properties • Circles and Triangles • Algebraic Fractions • Dividing Polynomials 	<ul style="list-style-type: none"> • Completing the square when a is not 1 • Determining and using the discriminant. Solving disguised quadratic equations using substitution. • Solving linear simultaneous equations by elimination and substitution. • Solving linear & quadratic simultaneous equations by substitution. $y-y_1=m(x-x_1)$ and $ax+by+c=0$ <p>Be able to use straight line graphs to solve rate of change problems</p> <ul style="list-style-type: none"> • Solving linear simultaneous equations by elimination and substitution. • Solving linear & quadratic simultaneous equations by substitution. • Solving linear inequalities. Solving quadratic inequalities. • Be able to express solutions with the correct use of 'and' and 'or', and using set notation. • e.g. $\{x: x>3\} \cup \{x: -2\leq x\leq 4\}$. • Be able to represent solutions on a number line and inequalities graphically. Be able to use interval 	<p>Quadratics</p> <ul style="list-style-type: none"> • Quadratic Equation: An equation of the form $ax^2+bx+c=0$ $ax^2 + bx + c = 0$ • Roots/Solutions: The values of xxx that satisfy the equation. • Discriminant: $D=b^2-4ac$ $D = b^2 - 4ac$; determines the nature of the roots. • Vertex: The highest or lowest point of the parabola. • Axis of Symmetry: The vertical line that passes through the vertex. • Factoring: Expressing a quadratic as a product of two binomials. <p>Equations</p> <ul style="list-style-type: none"> • Linear Equation: An equation of the first degree. • Simultaneous Equations: A set of equations with the 	Assessment in class (November)

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		<ul style="list-style-type: none"> • The Factors Theorem • Proof • Pascal's Triangle • Factorial Notation • The Binominal Expansion • Solving Binomial Problems • Binomial Estimation 	<p>notation. e.g. (2,3), [2,3), and $[2, \infty)$.</p> <p>Represent linear and quadratic inequalities such as $y > x + 1$ and $y > ax^2 + bx + c$ graphically (using the relevant shading, dotted and solid line conventions).</p> <ul style="list-style-type: none"> • Be able to plot and sketch graphs (including their vertical and horizontal asymptotes) of quadratic, cubic, quartic, square root, reciprocal (both a/x and a/x^2) and exponential functions. • Be able to use a graph to identify the roots of an equation and graph intersections to solve equations. • Be able to interpret and use proportionality graphs. • Understand and use the equation for a circle, centre (a,b) and radius r. • Be able to complete the square to convert circle equation of form $x^2 + y^2 + 2gx + 2fy + c = 0$ to $(x-a)^2 + (y-b)^2 = r^2$ and vice versa • Finding the equation of a circle from its radius and a point on the circumference, and end points of a diameter. <p>Be able to use the properties of a circle:</p> <ul style="list-style-type: none"> • the angle in a semicircle is a right angle, • the perpendicular from the centre of a circle to a chord bisects the chord, 	<p>same variables that are solved together.</p> <ul style="list-style-type: none"> • Polynomial: An expression involving variables raised to whole number powers. • Rational Equation: An equation involving fractions with polynomials in the numerator and denominator <p>Inequalities</p> <ul style="list-style-type: none"> • Inequality: A relation that holds between two expressions that are not equal (e.g., $<, >, \leq, \geq, >, \leq, \geq, >, \leq, \geq$). • Interval Notation: A way to describe sets of numbers (e.g., $(a,b), [a, b), (a,b]$). • Graphing Inequalities: Representing solutions on a number line or coordinate plane. <p>Graph Transformations</p> <ul style="list-style-type: none"> • Translation: Shifting a graph vertically or horizontally. • Reflection: Flipping a graph over a line (e.g., x-axis, y-axis). • Stretch/Compression: Changing the scale of a 	
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			<ul style="list-style-type: none"> • the radius of a circle at a given point on its circumference is perpendicular to the tangent to the circle at that point. • Be able to identify the co-ordinates of intersection of a straight line and a circle or two circles. • Algebraic fractions • Dividing polynomials • Factor Theorem • Methods of proof • Draw graphs of $y=asinbx$, $y=acosbx$ and $y=atanbx$, where a & b are constants and be able to use their symmetries and periodicities. • Derive the exact values of sin, cos & tan of 0°, 30°, 45°, 60° & 90° and equivalent larger/negative angles. • Be able to use the graphs of $y=sinx$, $y=cosx$, $y=tanx$ to find all possible solutions. • Convert between degrees & radians and vice versa. • Draw graphs of trigonometric functions in radians. • Calculate the length of an arc and the area of a sector using radians. • Solving trigonometric equations using radians. 	<p>graph vertically or horizontally.</p> <ul style="list-style-type: none"> • Transformation: A function applied to a graph that changes its position or shape <p>Circles</p> <ul style="list-style-type: none"> • Circle Equation: $(x-h)^2+(y-k)^2=r^2$ $(x-h)^2+(y-k)^2=r^2$ where (h,k) is the center and r is the radius. • Diameter: A line segment that passes through the center and connects two points on the circle. • Circumference: The distance around the circle, calculated as $C=2\pi r$ • Chord: A line segment with both endpoints on the circle <p>Algebraic Methods</p> <ul style="list-style-type: none"> • Factorization: Breaking down an expression into simpler parts. • Completing the Square: A method used to convert a quadratic into vertex form. 	
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				<ul style="list-style-type: none">• Substitution: Replacing a variable with another expression.• Elimination: A method for solving simultaneous equations by removing a variable. <p>Trigonometric Ratios</p> <ul style="list-style-type: none">• Sine (sin): Ratio of the opposite side to the hypotenuse in a right triangle.• Cosine (cos): Ratio of the adjacent side to the hypotenuse.• Tangent (tan): Ratio of the opposite side to the adjacent side.• Reciprocal Ratios: Cosecant (csc), secant (sec), and cotangent (cot). <p>Radians</p> <ul style="list-style-type: none">• Radian: A measure of angle defined as the ratio of the length of the arc to the radius of the circle.• Conversion: $180^\circ = \pi$ radians; converting degrees to radians and vice versa.	
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				<ul style="list-style-type: none"> • Unit Circle: A circle with a radius of 1 used to define trigonometric functions 	
Michaelmas 2	<ol style="list-style-type: none"> 1) Binomial Theorem 2) Trig Identities and equations 3) Differentiation 4) Integrations 	<ul style="list-style-type: none"> • Sine and Cosine Rule • Solving triangle problems • Graphs of Sine, Cosine and Tangent • Transforming trigonometric graphs • Angles in all four quadrants • Exact Trig Values • Trig Identities • Trig Equations • Gradients of curves • Finding the derivative • Differentiating x^n • Differentiating Quadratics • Gradients, tangents and normal • Increasing and decreasing functions • Second Order Derivatives 	<ul style="list-style-type: none"> • Pascal's Triangle • Factorial notation • Binomial expansion • Binomial problem solving • Estimation • Derive and use the trigonometric identities; $\tan\theta = \sin\theta/\cos\theta$ and $\sin^2\theta + \cos^2\theta = 1$. • Be able to solve trigonometric equations in a given interval, including quadratics equations in sin, cos, and tan, and equations involving multiples of the unknown angle. • Differentiation from first principles (for small positive powers of x) to find the gradient. • Differentiating simple polynomial expressions with positive and negative integer powers. • Finding stationary points of quadratic and cubic functions. • Find the range of x values for increasing and decreasing functions. 	<p>Binomial Theorem</p> <ul style="list-style-type: none"> • Binomial Expansion: The expansion of expressions of the form $(a+b)^n$. • Coefficient: The numerical factor in front of a term in the expansion. • Binomial Coefficient: Denoted as $\binom{n}{k}$ it represents the number of ways to choose k elements from n elements. • Term: Each individual part of the expanded expression. • Power: The exponent n in $(a+b)^n$ <p>Trigonometric Identities</p> <ul style="list-style-type: none"> • Pythagorean Identity: $\sin^2(x) + \cos^2(x) =$	Assessment in class (January)

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		<ul style="list-style-type: none"> • Stationary Points • Sketching Gradient Functions • Modelling with differentiation. • Integrating X^n • Indefinite integrals • Finding Functions • Definite Integrals • Areas under curves • Areas under the x axis • Areas between lines and curves 	<ul style="list-style-type: none"> • Basic curve sketching showing stationary points and y intercept. • Differentiate twice to find the rate of change of gradient and to find the nature of stationary points (points of inflection not included). • Find indefinite integrals of polynomials and be aware of possible exceptions. Find the equation of a function from its derivative and a point on the curve. Evaluate definite integrals, using relevant notation (including using calculator functions). • Use definite integration to find areas under curves. Evaluate improper integrals. 	<p>Differentiation</p> <ul style="list-style-type: none"> • Derivative: The rate of change of a function; denoted as $f'(x)$ or dy/dx • Critical Points: Points where the derivative is zero or undefined, indicating potential maxima or minima. <p>Integration</p> <ul style="list-style-type: none"> • Integral: The mathematical representation of the area under a curve. • Indefinite Integral: Represents a family of functions and includes a constant of integration. • Definite Integral: Represents the area under a curve between two points. 	
Lent 1	<ol style="list-style-type: none"> 1) Vectors 2) Exponentials and Logarithms 3) Large Data Set 4) Data Collections 5) Measures of Location and spread 6) Modelling in mechanics 	<ul style="list-style-type: none"> • Representing Vectors • Magnitude and Direction • Position Vectors • Solving Geometric Problems • Modelling with Vectors • Exponential Functions • $Y=e^x$ • Exponential modelling 	<ul style="list-style-type: none"> • Be able to represent vectors using column vectors, components of unit vectors and vector algebra, in two dimensions. • Calculate the magnitude and direction of a vector and convert between component 	<p>Vectors</p> <ul style="list-style-type: none"> • Vector: A quantity with both magnitude and direction, often represented as an arrow or in component form. • Magnitude: The length of a vector. 	Assessment in class (April)

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	<p>7) Constant acceleration</p>	<ul style="list-style-type: none"> • Logarithms • Laws of Logarithms • Solving Equations using logarithms • Working with natural logarithms • Logarithms and non-linear data. • Population and samples • Sampling • Non-random sampling • Types of data • Measures of central tendency and spread • Variance and standard deviation • Coding • Constructing a model • Modelling assumptions • Quantities and units • Displacement-time graphs • Velocity-time graphs • Constant acceleration formulae • Vertical motion under gravity 	<p>form and magnitude/direction form.</p> <ul style="list-style-type: none"> • Add vectors diagrammatically and perform the algebraic operations of vector addition and multiplication by scalars, and understand their geometrical interpretations. • Understand and use position vectors; calculate the distance between two points represented by position vectors. • Use vectors to solve problems in pure mathematics and in context, (including forces). • Understand exponential functions of the form a^x (where a is positive, including e) and draw their graphs. • Know that the gradient of e^{kx} is equal to ke^{kx} and hence understand why the exponential model is suitable in many applications. • Know and use the definition of $\log_a x$ as the inverse of a^x (where a is positive, including e – ie. $\ln x$). • Understand logarithms and convert between the exponential and logarithmic 	<ul style="list-style-type: none"> • Direction: The orientation of a vector, often expressed as an angle or a unit vector. • Unit Vector: A vector with a magnitude of 1. <p>Exponentials</p> <ul style="list-style-type: none"> • Exponential Function: A function of the form $f(x)=a^x$ • Base: The constant a in the exponential function. • Growth/Decay: Describes how quantities change over time; exponential growth increases rapidly, while exponential decay decreases. • Natural Exponential Function: Denoted ase^x, where e is Euler's number (≈ 2.718) <p>Logarithms</p> <ul style="list-style-type: none"> • Logarithm: The inverse of an exponential function. • Common Logarithm: The logarithm with base 10. • Natural Logarithm: The logarithm with base e. • Change of Base Formula: Allows conversion between logarithm bases.
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			<p>forms of a function. i.e $a=b^c$ is equivalent to $c=\log_b a$.</p> <ul style="list-style-type: none"> • Understand and use the laws of logs; i.e. $\log_a(xy)=\log_a x+\log_a y$, $\log_a(x/y)=\log_a x-\log_a y$, • $\log_a x^n=n\log_a x$, $\log_a a=1$ & $\log_a 1=0$. • Solve logarithmic and exponential equations. • Use logarithmic graphs to estimate parameters in relationships of the form $y = ax^n$ and $y = kb^x$, given data for x and y. (Plot $\log y$ against $\log x$ and obtain a straight line where the intercept is $\log a$ and the gradient is n Plot $\log y$ against x and obtain a straight line where the intercept is $\log k$ and the gradient is $\log b$.) • Understand and use exponential growth and decay; use in modelling (examples may include the use of e in continuous compound interest, radioactive decay, drug concentration decay, exponential growth as a model for population growth); consideration of limitations and refinements of exponential models. 	<p>Large Data Sets</p> <ul style="list-style-type: none"> • Population: The entire group being studied. • Sample: A subset of the population used for analysis. • Outlier: A data point that is significantly different from other observations. • Data Distribution: The way in which data values are spread or arranged. <p>Measures of Location and Spread</p> <ul style="list-style-type: none"> • Mean: The average of a data set, calculated as the sum of values divided by the number of values. • Median: The middle value when data is ordered from least to greatest. • Mode: The value that appears most frequently in a data set. • Variance: A measure of how much the values differ from the mean, calculated as the average of the squared differences. • Standard Deviation: The square root of the variance, 	
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			<ul style="list-style-type: none"> • Draw and transform exponential growth and exponential decay graphs. • Understand and be able to use sampling techniques, including simple random sampling and opportunity sampling. • Be able to select or critique sampling techniques in the context of solving a statistical problem, including understanding that different samples can lead to different conclusions about the population. • Be able to calculate and interpret measures of central tendency and variation, including mean, median, mode, percentile, quartile, inter-quartile range, standard deviation and variance. • Includes understanding that standard deviation is the root mean square deviation from the mean. • Be able to calculate mean and standard deviation from a list of data, from summary statistics or from a frequency distribution, using calculator statistical functions. 	<p>representing the average distance from the mean.</p> <p>Modelling in Mechanics</p> <ul style="list-style-type: none"> • Model: A simplified representation of a real-world situation used to make predictions or analyse behaviours. • Assumptions: Simplifications made in the model (e.g., treating objects as particles, ignoring air resistance). • Force: A vector quantity that causes an object to accelerate, measured in Newtons (N). • Equilibrium: A state where the sum of forces and moments acting on an object is zero. <p>Constant Acceleration</p> <ul style="list-style-type: none"> • Acceleration: The rate of change of velocity, measured in m/s^2. • Kinematic Equations: Equations that describe motion under constant acceleration: 	
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			<ul style="list-style-type: none"> Includes understanding that, in the case of a grouped frequency distribution, the calculated mean and standard deviation are estimates. Understand the concepts of distance and speed as scalar quantities, and of displacement, velocity and acceleration as vector quantities. Be able to sketch and interpret displacement/time (t, x) graphs and velocity/time (t, v) graphs. Be able to use the equations of linear motion (SUVAT) to solve problems including constant acceleration, including vertical motion. Be able to derive the SUVAT equations using velocity time graphs and substituting one equation into another. 	<ul style="list-style-type: none"> Initial Velocity (u): The velocity of an object at the start of a time interval. Final Velocity (v): The velocity of an object at the end of a time interval. Displacement (s): The overall change in position of an object. 	
Lent 2	<ol style="list-style-type: none"> 1) Representations of Data 2) Probability 3) Conditional Probability 4) Statistical Distributions 5) Forces and Motion 6) Friction 	<ul style="list-style-type: none"> Outliers Box Plots Cumulative Frequency Histograms Comparing Data Correlations Linear regression Calculating probabilities Venn diagrams 	<ul style="list-style-type: none"> Be able to interpret tables and diagrams for single-variable data. e.g. vertical line charts, dot plots, bar charts, stem-and-leaf diagrams, box-and-whisker plots, cumulative frequency diagrams and histograms (with either equal or 	<p>Representations of Data</p> <ul style="list-style-type: none"> Data Set: A collection of related data points or values. Bar Chart: A graphical representation using bars to compare quantities across categories. 	Assessment (EOY)

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		<ul style="list-style-type: none"> • Mutually exclusive and independent events • Tree diagrams • Probability distributions • The Binomial distribution • Cumulative Probabilities • Force Diagrams • Forces as Vectors • Forces and acceleration • Motion in 2 dimensions • Connected Particles • Pulleys 	<p>unequal class intervals). Includes non-standard representations.</p> <ul style="list-style-type: none"> • Recognise and be able to interpret possible outliers in data sets and statistical diagrams. • Be able to clean data, including dealing with missing data, errors and outliers. • Recognise and be able to interpret possible outliers in data sets and statistical diagrams. • Be able to clean data, including dealing with missing data, errors and outliers. • Understand and be able to use simple, finite, discrete probability distributions, defined in the form of a table or a formula. • Be able to calculate probabilities using the binomial distribution, using appropriate calculator functions • Understand the vector nature of force and use directed line segments to represent forces in two dimensions. 	<ul style="list-style-type: none"> • Histogram: A graphical representation of the distribution of numerical data, showing frequency of data within specified intervals. • Box Plot (Box-and-Whisker Plot): A graphical summary of a data set that shows the median, quartiles, and potential outliers. • Scatter Plot: A graph that shows the relationship between two numerical variables. • Pie Chart: A circular statistical graphic divided into slices to illustrate numerical proportions. <p>Probability</p> <ul style="list-style-type: none"> • Probability: A measure of the likelihood of an event occurring, ranging from 0 to 1. • Sample Space (S): The set of all possible outcomes of a random experiment. • Event: A subset of the sample space, representing outcomes of interest. • Mutually Exclusive Events: Events that cannot occur at the same time (e.g., rolling a 3 or a 5 on a die). 	
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			<ul style="list-style-type: none"> • Be able to identify the forces acting on a system and represent them in a forces diagram. • Use vector addition to find the resultant of two or more forces. • Be able to split a force into two perpendicular resolved forces. • Understand and be able to use Newton's 1st Law: 'A particle that is at rest (or moving with constant velocity) will remain at rest (or moving with constant velocity) until acted upon by an external force.' • Understand and be able to use Newton's second law ($F=ma$) for motion in a straight line for bodies of constant mass moving under the action of constant forces. • Represent the contact force between two rough surfaces, the 'normal force' and 'frictional force'. Understand and use the concept of limiting friction and limiting equilibrium. 	<ul style="list-style-type: none"> • Independent Events: Events where the occurrence of one does not affect the occurrence of the other. <p>Conditional Probability</p> <ul style="list-style-type: none"> • Conditional Probability: The probability of an event occurring given that another event has already occurred, denoted as $P(A B)P(A B)P(A B)$. <p>Statistical Distributions</p> <ul style="list-style-type: none"> • Distribution: Describes how values are spread or arranged; includes discrete and continuous distributions. • Normal Distribution: A continuous probability distribution characterized by a symmetric, bell-shaped curve defined by its mean and standard deviation. • Binomial Distribution: A discrete distribution describing the number of successes in a fixed number of independent Bernoulli trials. • Poisson Distribution: A discrete distribution used to model the number of events 	
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			<ul style="list-style-type: none"> • Apply Newton’s 3rd Law to particles that are both at rest and moving with constant acceleration: ‘Every action has an equal and opposite reaction’. • Solve problems which may be modelled as the motion of two particles connected by a light inextensible string. • Be able to solve problems involving simple cases of equilibrium of forces on a particle in two dimensions. • Resolve forces into components. • Solve problems involving smooth or rough inclined planes. • Understand friction and the coefficient of friction. • Find an unknown force when a system is in equilibrium. • Solve statics problems involving weight, tension and pulleys. • Understand and solve problems involving limiting equilibrium. 	<p>occurring in a fixed interval of time or space.</p> <ul style="list-style-type: none"> • Standard Normal Distribution: A normal distribution with a mean of 0 and a standard deviation of 1. <p>Forces</p> <ul style="list-style-type: none"> • Force: A vector quantity that causes an object to accelerate, measured in Newtons (N). • Newton's Laws of Motion: Fundamental principles that describe the relationship between the motion of an object and the forces acting on it: <ol style="list-style-type: none"> 1. First Law: An object at rest stays at rest, and an object in motion stays in motion unless acted upon by a net external force. 2. Second Law: The acceleration of an object is directly proportional to the net force acting on it and inversely proportional to its mass 	
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			<ul style="list-style-type: none"> • Solve problems involving motion on rough or smooth inclined planes. • Solve problems involving connected particles that require the resolution of forces. 	<p>3. Third Law: For every action, there is an equal and opposite reaction.</p> <p>Motion</p> <ul style="list-style-type: none"> • Displacement: The overall change in position of an object, represented as a vector. • Velocity: The rate of change of displacement, measured in m/s; can be average or instantaneous. • Acceleration: The rate of change of velocity. • Kinematics: The study of motion without considering the forces that cause it. <p>Friction</p> <ul style="list-style-type: none"> • Friction: The resistance force that opposes the motion of two surfaces in contact. • Static Friction: The frictional force that prevents two surfaces from sliding past each other. • Kinetic Friction: The frictional force acting on an object in motion. 	
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				<ul style="list-style-type: none"> • Coefficient of Friction: A dimensionless scalar value that represents the frictional properties of the surfaces in contact; denoted as μ. • Normal Force: The perpendicular force exerted by a surface to support the weight of an object resting on it, counteracting gravity. 	
Trinity 1	<ol style="list-style-type: none"> 1) Hypothesis Testing 2) Application of Forces 3) Variable Acceleration. 	<ul style="list-style-type: none"> • Hypothesis testing • Finding Critical values • One-tailed tests • Two-tailed tests 	<ul style="list-style-type: none"> • Understand and be able to use the language of statistical hypothesis testing, developed through a binomial model: null hypothesis, alternative hypothesis, significance level, test statistic, 1-tail test, 2-tail test, critical value, critical region, acceptance region, p-value. • Be able to conduct a statistical hypothesis test for the proportion in the binomial distribution and interpret the results in context. • Understand that a sample is being used to make an inference about the population and appreciate that the significance level is the probability of 	<p>Hypothesis Testing</p> <ul style="list-style-type: none"> • Hypothesis: A statement or assumption that can be tested; typically involves a null hypothesis (H_0) and an alternative hypothesis (H_1). • Null Hypothesis (H_0): The hypothesis that there is no effect or no difference; it is what we aim to test against. • Alternative Hypothesis (H_1): The hypothesis that represents an effect or a difference; it is what we hope to support. • Significance Level (α): The threshold probability for rejecting the null hypothesis, commonly set at 0.05 or 0.01. • Test Statistic: A standardized value 	Assessment (EOY)

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			<p>incorrectly rejecting the null hypothesis.</p> <ul style="list-style-type: none">• Work with vectors for displacement, velocity and acceleration when using the vector equations of motion.• Use calculus with harder functions of time involving variable acceleration.• Differentiate and integrate vectors with respect to time.	<p>calculated from sample data that is used to determine whether to reject the null hypothesis.</p> <ul style="list-style-type: none">• P-Value: The probability of obtaining a test statistic as extreme as the one observed, under the assumption that the null hypothesis is true.• Confidence Interval: A range of values that is likely to contain the population parameter with a certain level of confidence (e.g., 95%). <p>Application of Forces</p> <ul style="list-style-type: none">• Resultant Force: The single force that represents the combined effect of all forces acting on an object.• Equilibrium: A state where all forces acting on an object are balanced, resulting in no net force and no acceleration.• Tension: The force transmitted through a string, rope, or cable when it is pulled tight.• Normal Force: The perpendicular force exerted by a surface to support the	
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				<p>weight of an object resting on it.</p> <ul style="list-style-type: none">• Frictional Force: The force that opposes the relative motion of two surfaces in contact.• Weight: The force acting on an object due to gravity. <p>Variable Accelerations</p> <ul style="list-style-type: none">• Variable Acceleration: Acceleration that changes over time; can be due to changing forces acting on an object.• Differentiation: The mathematical process used to find the instantaneous rate of change of a function, often used to find acceleration from velocity.• Kinematic Equations for Variable Acceleration: Equations that relate displacement, velocity, and time when acceleration is not constant, often requiring calculus for solutions.• Velocity-Time Graph: A graphical representation showing how velocity changes over time; the slope of the graph represents acceleration.	
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				<ul style="list-style-type: none">• Acceleration-Time Graph: A graph showing how acceleration changes over time; the area under the graph represents change in velocity	
Trinity 2	1) Algebraic Methods	<ul style="list-style-type: none">• Be able to add / subtract, multiply / divide algebraic fractions, and simplify them by cancelling down.			